QLA-360MPT-40 AUTO ACQUISITION and PROGRAM TRACKING FOR SATELLITES





The QLA-360MPT-40 is designed from the ground up to automatically point directional antennas for satellite communications.

The embedded antenna controller with built in GPS and digital compass has a full featured web based user interface which provides rapid and accurate antenna pointing. The user interface includes manual control and status along with a stored satellite database and two line element set program track capability which allows easy tracking of satellites in low or medium earth orbit. Nextmove also has a command line interface for customers that want to add our solution into a larger system.

The QLA-360MPT-40 is typically paired with 3-6 ft antennas, payloads up to 200 lbs (90.7 kg), and offers 360° of azimuth and $\pm 90^{\circ}$ (180°) of elevation range. Optional cross elevation accessory available to eliminate keyhole effect for overhead passes.

	TECHNICAL SPECIFICATIONS - LinkAlign-360MPT-40			
Power	Power Over Ethernet (POE) 48VDC Supply Included			
Material / Finish	Aluminum with stainless steel hardware / Hard coat anodize			
Positioner Travel				
Azimuth	400° (+/-200°)			
Elevation	180° (+/-90°)			
Positioner Drive Rate				
Azimuth	Variable, up to 12°/sec no load			
Elevation	Variable, up to 7°/sec no load			
Temperature				
Operational	-22 to 140°F (-30 to 60°C)			
Survival	-40 to 158°F (-40 to 70°C)			
Feedback Resolution	0.1°			
Backlash (Az/El)	less than 0.1°			
Torque				
Continuous (Az/El)	25 ft-lbs / 40 ft-lbs (33.9 Nm / 54.2 Nm)			
Peak (Az/El)	53 ft-lbs / 80 ft-lbs (71.9 Nm / 108.5 Nm)			
Holding Non-Powered (Az/El)	13 ft-lbs / 20 ft-lbs (17.6 Nm / 27.1 Nm)			
Payload (Including Counterweights)	200 lbs (90.7 kg)			
Dimensions	Height: 21.38" (54.3 cm), Width: 11.50" (29.2 cm), Depth: 16.00" (40.6 cm)			
Weight	99 lbs (44.9 kg) without Counterweight Kit			
Mounting Interface	Table top mount (See ICD for details) Picture shown mounted to optional pedestal riser			
Antenna Mount Options	1/2-13 threaded holes or 1/2" fastener clearance holes (See ICD for details)			
Communication Interface				
User Interfaces	Web based hosted internal to unit or Nextmove proprietary command protocol			
Ethernet	10/100 Ethernet			
Serial	RS-232			
Other	Satellite Modem Interfaces for Acquistion and Tracking			

Q-PAR Antennas USA, LLC - sales@qparusa.com - Tel: 702-208-9973 - Fax: 702-208-9984

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NOTE	S: UNLESS OTHERWISE SP	ecified							
С	LA-360MPT-40 CONFIGU OUNTERWEIGHTS. LINKA OUNTERWEIGHTS (EQUIV	ALIGN-360MPT-40	SUPPLIED WI	ITH 60 LBS OF					
2. US	SE INTERFACE CONTROL	DRAWING IN CO	ONJUNCTION	I WITH DATAS	SHEET N500159				
3. SE	E TABLE II FOR AVAILAB	LE LINKALIGN-360)MPT-40 ACC	CESSORY OP1	IONS				\supset
4. 48	3VDC POWER SUPPLY IN	ICLUDED WITH PC	DSITIONER. NO	n Nohs TC	N DRAWING			a	_
5. H.	ARD COAT ANODIZE AL	UMINUM CONSTR	RUCTION WIT	H STAINLESS S	STEEL HARDWARE			\bigcirc	
6. 40	00° (+/-200°) AZIMUTH TR	RAVEL WITH 12°/SE	EC DRIVE RA	te (no loae)))	
7.18	30° (+/-90°) ELEVATION T	IRAVEL WITH 7°/SI	EC DRIVE RA	te (no loae))			\sim	
82 7(2° TO 140°F (-30° TO 60°)°C) NON-OPERATIONA	°C) OPERATIONAL L TEMPERATURE R	L TEMPERATU ANGE	RE RANGE	40 TO 158°F (-40 TC)	0		\circ \subset
9. 0.	1° FEEDBACK RESOLUTIO	ON IN ALL AXES							
10. A	ZIMUTH AND ELEVATION	BACKLASH LESS	THAN 0.1°						
11 21 AF	.38" (54.3 cm) HIGH X 1 PPLY WHEN POSITIONER	1.50" (29.2 cm) W IS AT 0° AZIMUTH	IDE X 16.00" AND 0° ELEV	(40.6 cm) DE ATION ANGI	ep. dimensions .es				
	EIGHT APPROXIMATELY							/	
B/ C P/ W	AYLOAD SHALL NOT EXC) FT-LBS OF TORQUE ABC ALANCE ELEVATION PAY OUNTERWEIGHTS PROVI AYLOAD CENTER OF GR (EIGHT, POSITIONER IS B) ODE, ELEVATION HOLDI	YLOAD AS MUCH IDED. TO CALCUL AVITY TO DATUM ACKDRIVABLE WI	AS POSSIBLE ATE TORQUE -B- IN FEET A HEN NOT PO	BY USING TH , TAKE THE D ND MULTIPLY WERED UP O	ie (6) 10 lb Istance from the ' by the payload	Ξ			
14 TA	ABLE TOP MOUNTING HO	Oles						O	
	ENTER OF GRAVITY 0.2" DIRECTION AND 0.2" (0.5 CONTINUED ON SHEET 6		-DIRECTION, ECTION	9.2" (23.4 cm	n) IN THE Y-			• •	e e
_									\ 0
-			TABLE I	10					FRONT
	BUILDING A PART NU	<u></u>		15					
			ETHERNET CABL	E STANDARD LE	NGTHS				
		100 =	= 100 ft = 150 ft					0	E C
		250 =	200 ft 250 ft						
		XXX =	 300 ft Custom length in 						
			CONFIGURATION	cable length for un	terminated mating connector	r			
			Standard options -	leave blank		—			
		40 =				—			
					°/s, 200 lb payload. Typically imuth, +/-90° elevation)				
		MODEL LA-360MPT =	: LinkAlian-360MPT	(See motor drives	and payload section for	_			
			positioner travel ra		, ,				

TABLE II (MPT-40 ACCESSORY OPTIONS)						
ACCESSORY DESCRIPTION	ACCESSORY PART NUMBER	ACCESSORY ICD				
RISER ASSEMBLY, MPT-40	ACC-N900553-XX	ICDN900553				
CROSS ELEVATION DRIVE ASSEMBLY KIT, MPT-40	ACC-N900555-1	ICDN900555				
QUADPOD, MPT-40	ACC-N900577-1	ICDN900577				
transit case, mpt-40	TC-LA-360MPT-40-1	N/A				

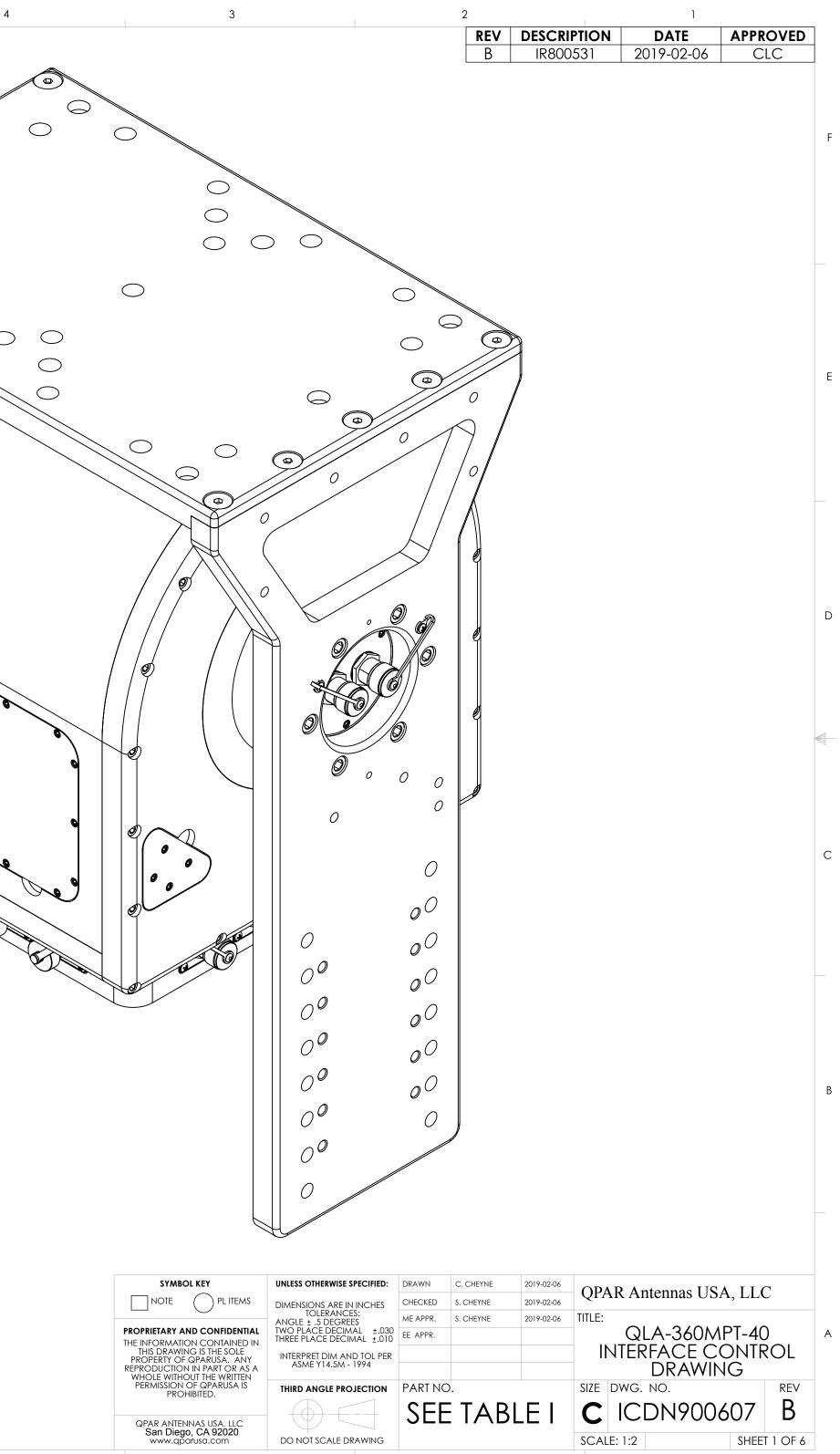
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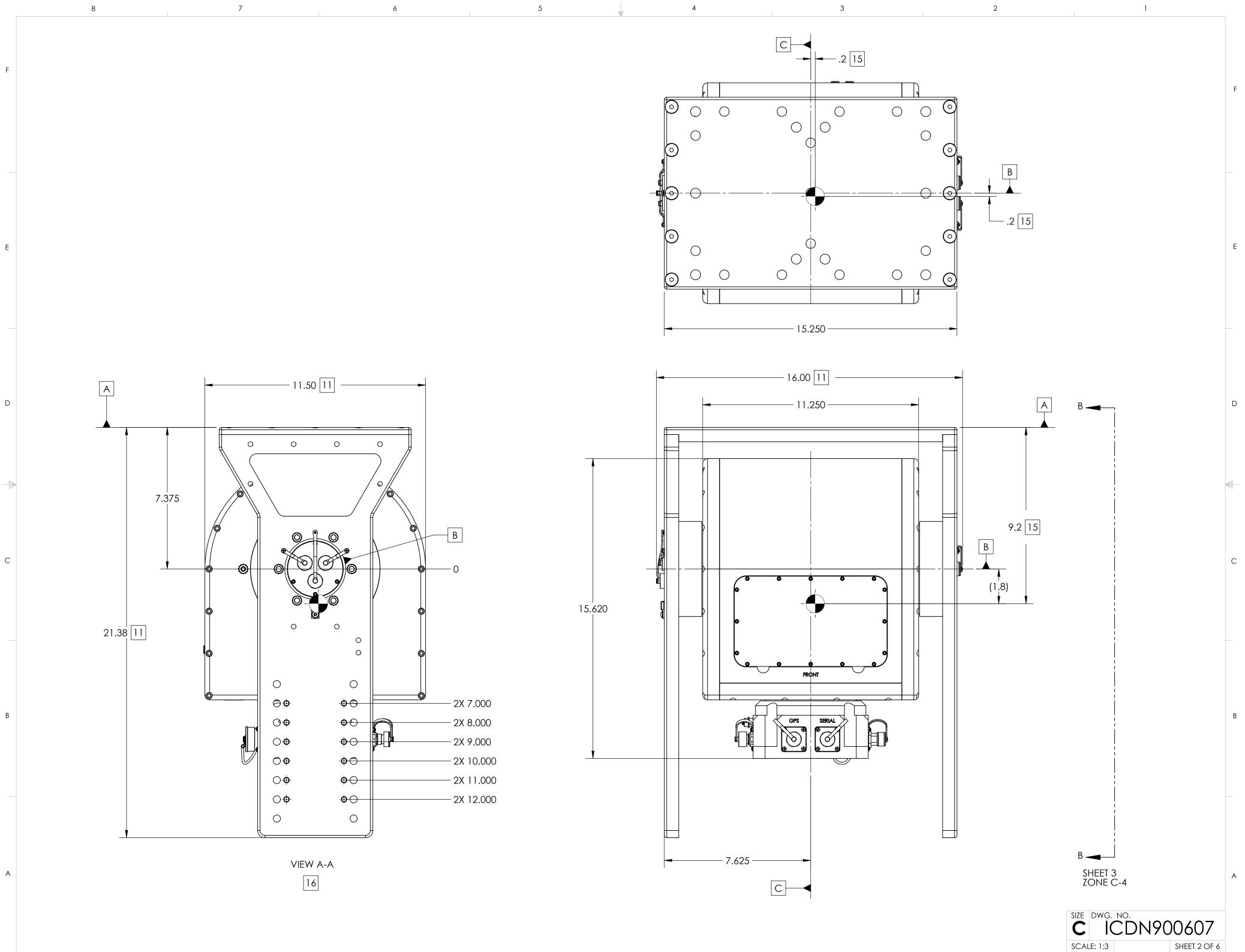
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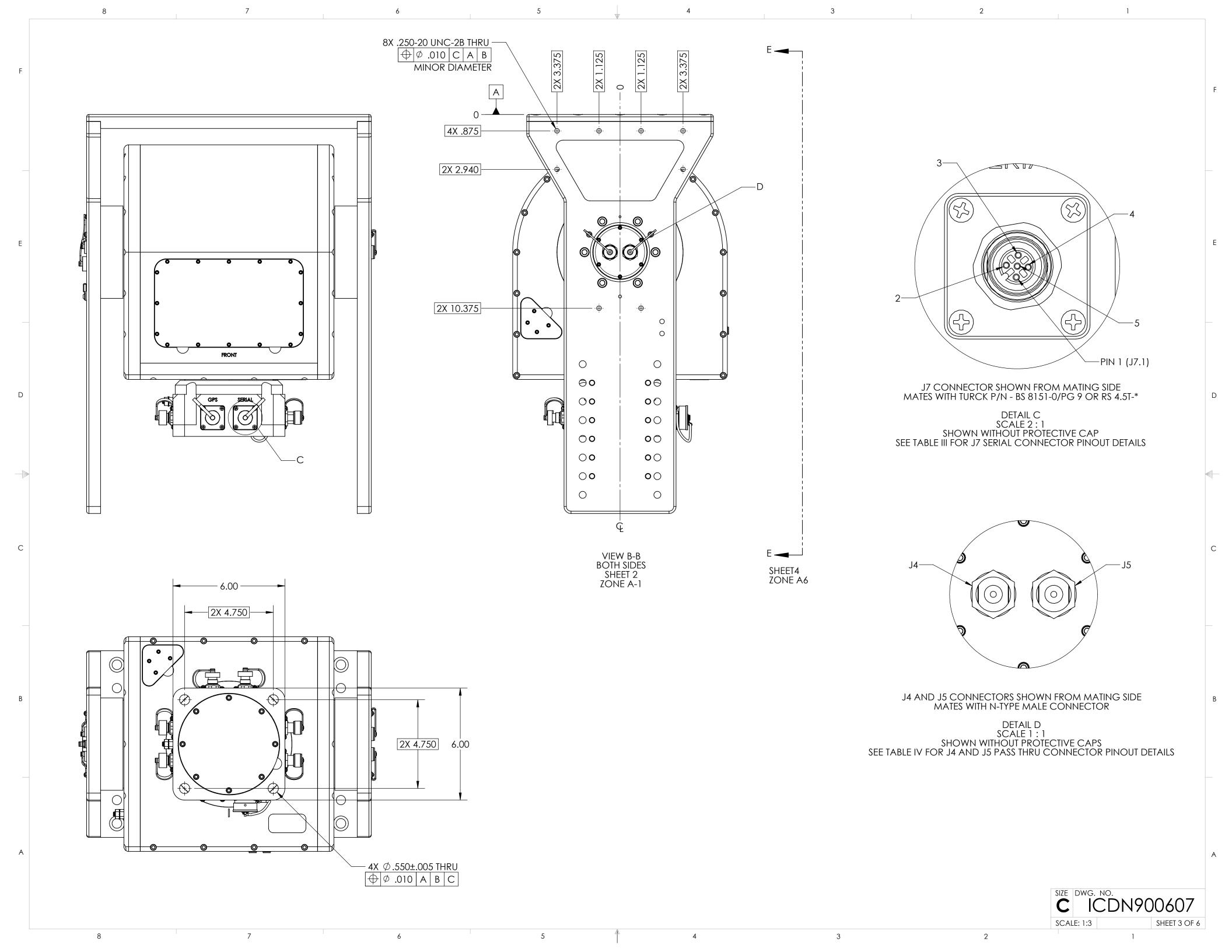
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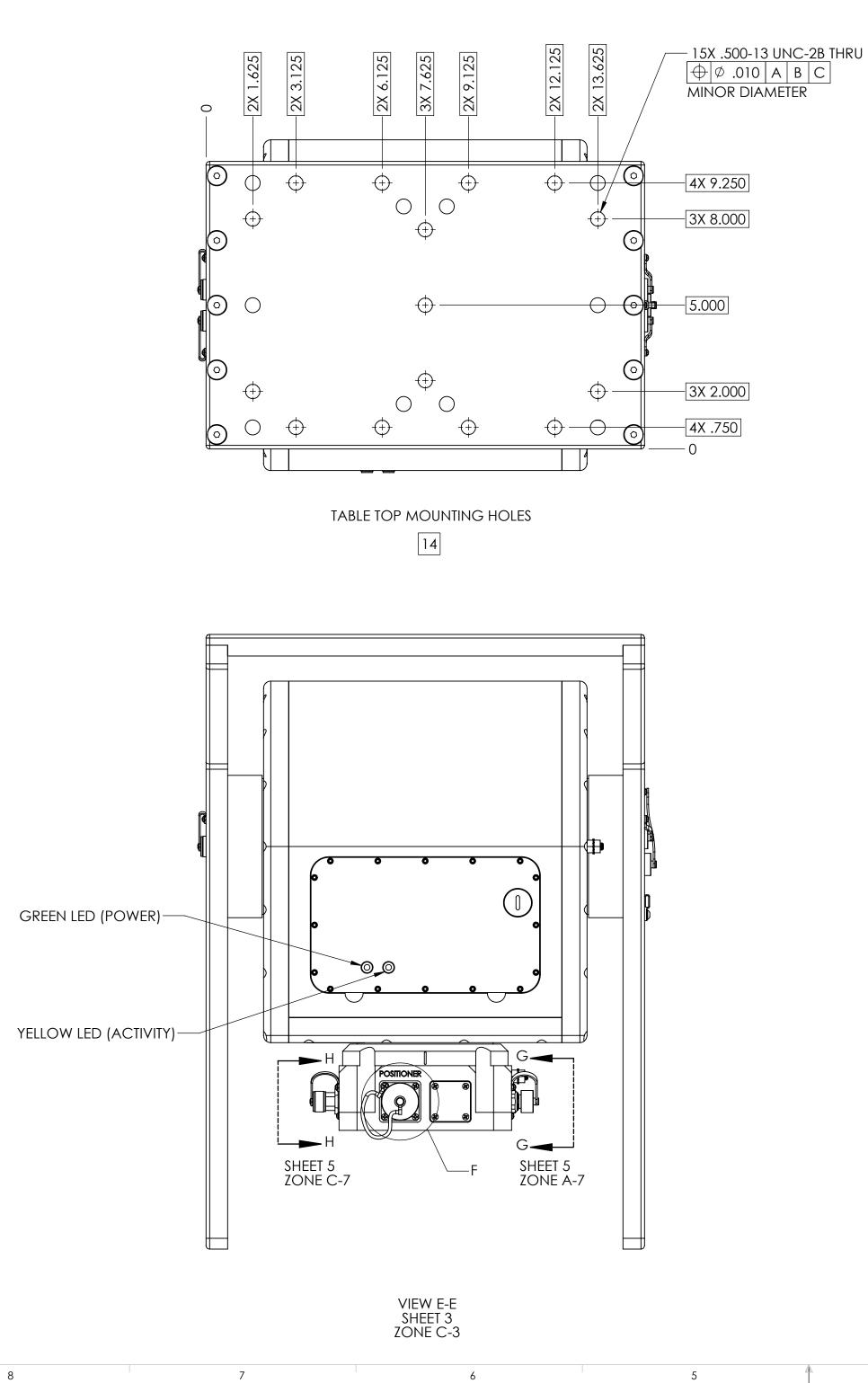
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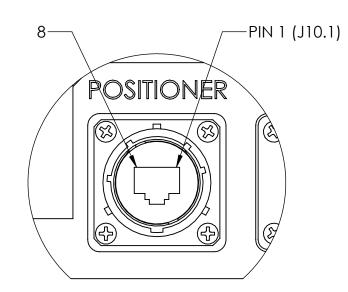
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GND STUD-

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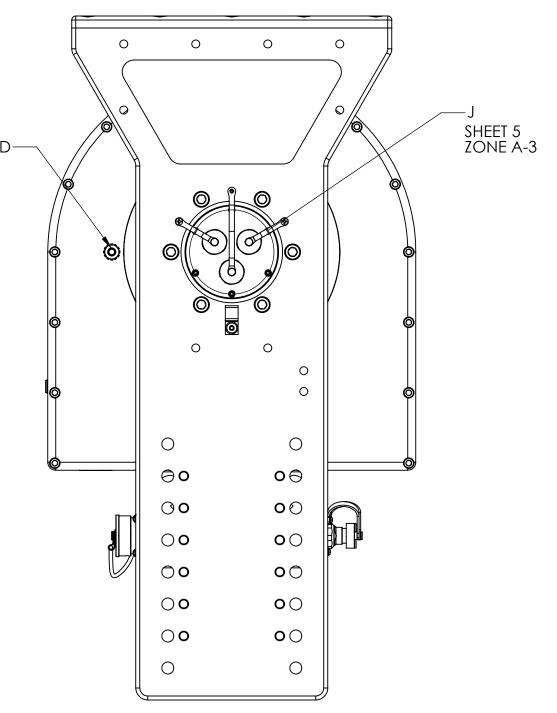
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J10 CONNECTOR SHOWN FROM MATING SIDE MATES WITH AMPHENOL P/N RJF68

DETAIL F SCALE 1 : 1 SHOWN WITHOUT PROTECTIVE CAP SEE TABLE III FOR J10 CONNECTOR PINOUT DETAILS



SIZE DWG. NO. SCALE: 1:3 SHEET 4 OF 6

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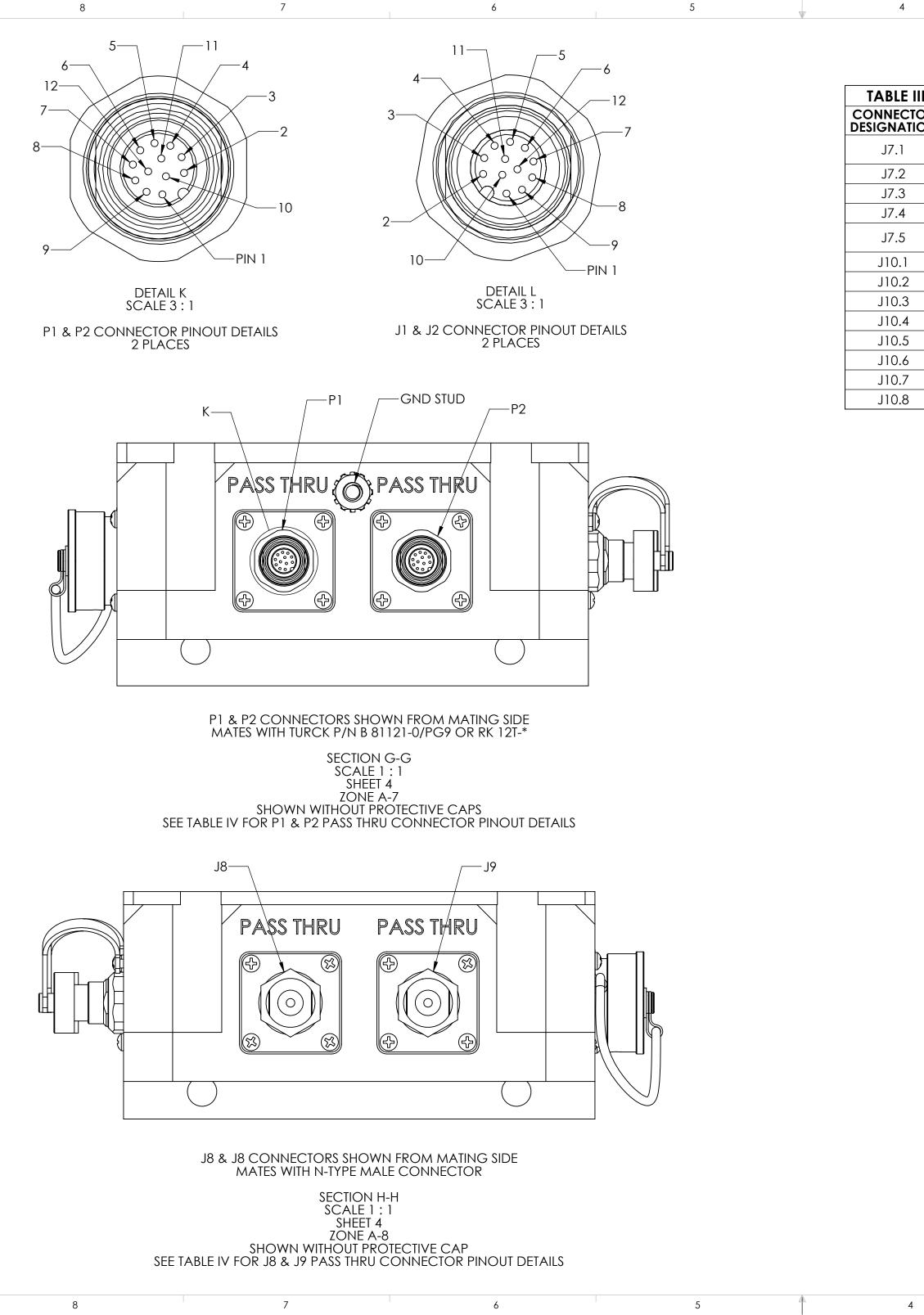
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II (CONNECTOR FUNCTION)					
FUNCTION					
dc return for qparusa Joystick					
NOT USED					
(B) TxD+/RxD+ DATA LINE					
(A) TxD-/RxD- DATA LINE					
dc power for qparusa Joystick					
DATA PAIR 1					
DATA PAIR 1					
DATA PAIR 2					
+48-56VDC PoE POWER INPUT					
+48-56VDC PoE POWER INPUT					
DATA PAIR 2					
DC RETURN FOR POE INPUT					
DC RETURN FOR POE INPUT					

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TABLE IV (WIRING DIAGRAM)			
FROM	TO		
P1.1	J1.1		
V			
P1.12	J1.12		
P2.1	J2.1		
P2.12	J2.12		
J8.1	J4.1		
J9.1	J5.1		

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